



Barum Czech Rally Zlín 2017

25. 08. 2017 - 27. 08. 2017

Nieoficjalne wyniki
Zestawienie dla klasy: **RC4**
OS **SHAKEDOWN - Zlutava**
Długość OS: **4.55 km**



Poz.	Nr	Kierowca / Pilot Samochód	Klasa	Czas OS	Śred. prędkość s/km	Strata do lidera Strata do poprz.
1	71	Kamenec Matěj / Jurka Adam Peugeot 208 R2	RC4	00:03:13.700 > 00:03:07.300 > 00:03:03.800 > 00:03:04.200 > 00:03:02.800	89.61 0.00	00:00:00.000 00:00:00.000
2	70	Furuseth Sindre / Eriksen T. Opel Adam R2	RC4	00:03:11.400 > 00:03:04.000 > 00:03:03.200	89.41 0.09	00:00:00.400 00:00:00.400
3	73	Knápek Tomáš / Horák Ivan Peugeot 208 R2	RC4	00:03:17.600 > 00:03:11.100 > 00:03:08.100	87.08 1.16	00:00:05.300 00:00:04.900
4	83	Firla Lumír / Topič Marek Peugeot 208 R2	RC4	00:03:17.700 > 00:03:10.600 > 00:03:10.500 > 00:03:09.400	86.48 1.45	00:00:06.600 00:00:01.300
5	82	Březík Adam / Voltner Karel Peugeot 208 R2	RC4	00:03:21.300 > 00:03:13.900 > 00:03:10.200	86.12 1.63	00:00:07.400 00:00:00.800
6	74	Pospíšilík T. / Hovorka Jiří Peugeot 208 R2	RC4	00:03:15.700 > 00:03:10.300 > 00:03:37.000	86.07 1.65	00:00:07.500 00:00:00.100
7	79	Svačina Marcel / Kouřil Martin Peugeot 208 R2	RC4	00:03:13.700 > 00:03:10.400 > 00:03:13.000 > 00:03:13.000 > 00:03:18.400	86.03 1.67	00:00:07.600 00:00:00.100
8	81	Hordossy Robert / Palivec Š. Opel Adam R2	RC4	00:03:23.000 > 00:03:14.100 > 00:03:29.100 > 00:03:13.300 > 00:03:10.500	85.98 1.69	00:00:07.700 00:00:00.100
9	72	Barčák Andrej / Střeska T. Opel Adam R2	RC4	00:03:23.000 > 00:03:15.800 > 00:03:15.300 > 00:03:13.500	84.65 2.35	00:00:10.700 00:00:03.000
10	88	Lechoszewski A. / Sitek Łukasz Peugeot 208 R2	RC4	00:03:31.200 > 00:03:21.200 > 00:03:33.400 > 00:03:17.300 > 00:03:20.200 00:03:19.900	83.02 3.19	00:00:14.500 00:00:03.800
11	90	Stratieva E. / Avramov Georgi Citroën C2 R2 Max	RC4	00:03:55.100 > 00:03:40.900 > 00:03:36.600 > 00:03:32.500 > 00:03:33.500	77.08 6.53	00:00:29.700 00:00:15.200
12	91	Martínek Roman / Nesvadba R. Honda Civic Type R	RC4	00:03:43.100 > 00:03:40.500	74.29 8.29	00:00:37.700 00:00:08.000